

# Examples of Minimal Surfaces

Michael Beeson

March 9, 2015

## Contents

<b>1</b>	<b>Enneper's Surface</b>	<b>2</b>
1.1	Weierstrass representation . . . . .	2
1.2	Non-parametric form . . . . .	2
1.3	total curvature of Enneper's wire . . . . .	3
1.4	Self-intersection . . . . .	3
1.5	First and second eigenvalues . . . . .	3
1.6	Ruchert's uniqueness theorem . . . . .	3
1.7	The second variation of $D^2E$ . . . . .	3
1.8	The third variation of Enneper's surface . . . . .	4
1.9	The fourth variation of Enneper's surface . . . . .	6
1.10	Relative minimum for $R = 1$ . . . . .	8
1.11	Trifurcation and the cusp catastrophe . . . . .	9
<b>2</b>	<b>The catenoid</b>	<b>9</b>
2.1	Weierstrass representation . . . . .	9
2.2	Non-parametric form . . . . .	9
2.3	Unique minimal surface of revolution . . . . .	9
2.4	Existence between coaxial circles in parallel planes . . . . .	9
2.5	Stability . . . . .	9
2.6	The second variation . . . . .	9
<b>3</b>	<b>The helicoid</b>	<b>9</b>
3.1	Weierstrass representation . . . . .	9
3.2	Non-parametric form . . . . .	9
3.3	Unique ruled minimal surface . . . . .	9
3.4	Second variation of $D^2A$ . . . . .	9
3.5	The second, third, and fourth variations of $D^2E$ . . . . .	9
3.6	Trifurcation and the cusp catastrophe . . . . .	9
<b>4</b>	<b>Scherk's surface</b>	<b>9</b>
4.1	Weierstrass representation . . . . .	9
4.2	Non-parametric form . . . . .	9
4.3	Use as a comparison surface . . . . .	9

# 1 Enneper's Surface

Enneper's surface was discovered in 1863 by Alfred Enneper, who was 33 at the time. This was seven years after his Ph. D. under the supervision of Dirichlet at Göttingen, where Enneper lived his entire life, from student to Professor Extraordinarius.

Enneper's surface is defined in the entire complex plane, so it is an example of a complete minimal surface (no boundary). However, we are interested in considering portions of it, defined in a disk of radius  $R$ . Then it is bounded by "Enneper's wire",

$$\Gamma_R(\theta) = \begin{bmatrix} R \cos \theta - \frac{1}{3}R^3 \cos 3\theta \\ -R \sin \theta + \frac{1}{3}R^3 \sin 3\theta \\ R^2 \cos 2\theta \end{bmatrix}$$

The same formula, with  $r$  in place of  $R$ , defines Enneper's surface in polar coordinates.

## 1.1 Weierstrass representation

To show that Enneper's surface as defined above is indeed a minimal surface, we show that it arises from the Weierstrass representation if we take  $f(z) = 2$  and  $g(z) = 2z$ . This gives us

$$u_z = \begin{bmatrix} 1 - z^2 \\ i(1 + z^2) \\ 2z \end{bmatrix}$$

Integrating, we have

$$\begin{aligned} u &= \operatorname{Re} \begin{bmatrix} z - \frac{1}{3}z^3 \\ i(z + \frac{1}{3}z^3) \\ z^2 \end{bmatrix} \\ &= \begin{bmatrix} r \cos \theta - \frac{1}{3}r^3 \cos 3\theta \\ -r \sin \theta + \frac{1}{3}r^3 \sin 3\theta \\ r^2 \cos 2\theta \end{bmatrix} \end{aligned}$$

## 1.2 Non-parametric form

According to Rado's theorem, as long as the Jordan curve  $\Gamma$  has a convex project on the  $xy$  plane, any disk-type minimal surface bounded by  $\Gamma$  is expressible in non-parametric form, i.e.  $z = f(x, y)$ . Since there is a maximum principle for the difference of two solutions of the non-parametric minimal surface equation, the solution for a given boundary is unique.

Let  $\Gamma_R$  be "Enneper's wire", defined above.

**Lemma 1** *For  $R \leq \frac{1}{\sqrt{3}}$ , the projection of Enneper's wire  $\Gamma_R$  on the  $xy$  plane is convex. Hence  $\Gamma_R$  bounds exactly one minimal surface.*

*Proof.* Let  $\gamma_\rho$  be the projection of  $\Gamma_\rho$  onto the  $xy$  plane. Then

$$\gamma_\rho(\theta) = \begin{bmatrix} \rho \cos \theta - \frac{1}{2}\rho^3 \cos 3\theta \\ -\rho \sin \theta + \frac{1}{3}\rho^3 \sin 3\theta \end{bmatrix}$$

*History and references.* See pp. 80-84 of [17]; see also [19] ? and [?] ?

### 1.3 total curvature of Enneper's wire

### 1.4 Self-intersection

### 1.5 First and second eigenvalues

### 1.6 Ruchert's uniqueness theorem

### 1.7 The second variation of $D^2E$

Consider the kernel equation for Enneper's surface in the disk of radius 1,

$$k_z u_z = 0$$

or in real form with  $k = \psi u_\theta$ ,

$$u_\theta((\psi u_\theta)_r - (\psi u_r)_\theta) = 0.$$

We will show that  $\psi = \sin(2\theta)$  solves this equation. On  $S^1$  we have (even when  $t \neq 0$ )

$$\begin{aligned} k &= \psi u_\theta \\ &= \sin 2\theta \operatorname{Re} (izu_z) \\ &= \frac{1}{2}i(z^2 - \bar{z}^2) \operatorname{Re} \begin{bmatrix} i(z - z^3) \\ -(z + z^3) \\ 2iz^2 \end{bmatrix} \\ &= \frac{1}{4}i(z^2 - \bar{z}^2) \begin{bmatrix} -iz^3 + iz - i\bar{z} + i\bar{z}^3 \\ -z^3 - z - \bar{z} - \bar{z}^3 \\ 2iz^2 - 2i\bar{z}^2 \end{bmatrix} \\ &= \frac{1}{4} \begin{bmatrix} (z^2 - \bar{z}^2)(z^3 - z + \bar{z} - \bar{z}^3) \\ -i(z^2 - \bar{z}^2)(z^3 + z + \bar{z} + \bar{z}^3) \\ -(z^2 - \bar{z}^2)(2z^2 - 2\bar{z}^2) \end{bmatrix} \\ &= \frac{1}{4} \begin{bmatrix} z^5 - z^3 - \bar{z}^3 + \bar{z}^5 \\ -i(z^5 + z^3 - \bar{z}^3 - \bar{z}^5) \\ -2z^4 + 4 - 2\bar{z}^4 \end{bmatrix} \end{aligned}$$

This expression for  $k$  is harmonic in the entire plane since evidently  $\Delta k = k_{z\bar{z}} = 0$ . Differentiating with respect to  $z$  we have (even when  $t \neq 0$ )

$$k_z = \frac{1}{4} \begin{bmatrix} 5z^4 - 3z^2 \\ -5iz^4 - 3iz^2 \\ -8z^3 \end{bmatrix} \quad (1)$$

Taking the dot product with  $u_z$  we have, when  $t = 0$ ,

$$\begin{aligned} k_z u_z &= \frac{1}{4} \begin{bmatrix} 5z^4 - 3z^2 \\ -5iz^4 - 3iz^2 \\ -8z^3 \end{bmatrix} \cdot \begin{bmatrix} 1 - z^2 \\ i(1 + z^2) \\ 2z \end{bmatrix} \\ &= \frac{1}{4} \begin{bmatrix} 5z^4 - 3z^2 \\ 5z^4 + 3z^2 \\ -8z^3 \end{bmatrix} \cdot \begin{bmatrix} 1 - z^2 \\ 1 + z^2 \\ 2z \end{bmatrix} = 0 \end{aligned}$$

Similar calculations show that  $\psi = a + b \cos \theta + c \sin \theta$  also yields a solution; this three-parameter family accounts for the conformal directions, and  $\psi = 2 \cos \theta$  represents a non-trivial kernel direction.

That  $k$  is the only kernel direction (orthogonal to the conformal directions) can be shown directly by writing a Fourier series for an unknown  $\psi = \sum_{n=-\infty}^{\infty} a_n z^n$  on  $S^1$  and showing  $\psi$  must have the form  $a + b \cos \theta + c \sin \theta + d \sin 2\theta$ , which is how we found  $\psi = \sin 2\theta$  in the first place.

We also give a more informative proof that  $k$  is the only non-trivial kernel direction. The function  $g(z)$  in the Weierstrass representation is the stereographic projection of the unit normal  $N$ , and for Enneper's surface  $g(z) = z$ . Hence, the Gaussian image of Enneper's surface in the unit disk is exactly the upper hemisphere. Hence the first eigenvalue of  $D^2 A(u)$  is 2, so the kernel of  $D^2 A(u)$  is one-dimensional, as the eigenspace of the least eigenvalue. But every member  $k$  of the kernel of  $D^2 E(u)$  gives rise to a member  $\phi = k \cdot N$  of the kernel of  $D^2 A(u)$ , and the map  $k \mapsto \phi$  is one to one.

For  $R < 1$ , the Gaussian area of Enneper's surface over the disk of radius  $R$  is contained in a hemisphere, so the critical eigenvalue is more than 2 and the surface is a relative minimum of area. For  $R > 1$ , the Gaussian area contains a hemisphere, so the surface is not a relative minimum of area. Hence  $R = 1$  is the only value for which the second variation has a kernel.

## 1.8 The third variation of Enneper's surface

We now calculate the third variation of Enneper's surface (defined in the unit disk). We consider a variation  $u(t)$  defined on  $S^1$  by

$$u = u_0(e^{i(\theta + t\psi + O(t^2))})$$

where  $\psi(\theta) = \sin 2\theta$  and the subscript in  $u_0$  indicates  $t = 0$ . Differentiating with respect to  $t$  we have

$$u_t = (\psi + O(t))u_\theta.$$

Thus  $k = u_t$  lies in the kernel of  $D^2 E(u_0)$  when  $t = 0$ .

**Lemma 2** *The third variation of Enneper's surface is zero. Specifically, with the variation  $u(t)$  given above, we have*

$$\left. \frac{\partial^3 E}{\partial t^3} \right|_{t=0} = 0.$$

*Proof.* We have (as shown in Lectures on Minimal Surfaces, Chapter 10, following [24])

$$\left. \frac{\partial^3 E}{\partial t^3} \right|_{t=0} = 4 \operatorname{Re} \int z k_z^2 \psi dz + 4 \operatorname{Re} \int z (\psi k_\theta)_z u_z \psi dz \quad (2)$$

By (1) we have  $k_z = z^2 v$  for some holomorphic vector  $v$ . Then  $k_z^2 = z^4 v^2$ . Then on  $S^1$  we have

$$\begin{aligned} z k_z^2 \psi &= z^5 v^2 \frac{i}{2} (z^2 - \bar{z}^2) \\ &= z^3 v^2 \frac{i}{2} (z^4 - 1) \end{aligned}$$

The integrand is holomorphic in the unit disk, so by Cauchy's theorem, the first integral in (2) is zero.

We now work on the second integral. From (1) we have

$$z k_z = \frac{1}{4} 5z^5 - 3z^3 - 5iz^5 - 3iz^3 - 8z^4$$

Then

$$\begin{aligned} k_\theta &= -\operatorname{Im} (z k_z) = -2i(z k_z + \bar{z} \overline{z k_z}) \\ &= \frac{1}{2} \begin{bmatrix} -5iz^5 + 3iz^3 - 3i\bar{z}^3 + 5i\bar{z}^5 \\ -5z^5 - 3z^3 - 3\bar{z}^3 - 5\bar{z}^5 \\ 8iz^4 - 8i\bar{z}^4 \end{bmatrix} \\ \psi k_\theta &= \frac{-i}{4} (z^2 - \bar{z}^2) \begin{bmatrix} -5iz^5 + 3iz^3 - 3i\bar{z}^3 + 5i\bar{z}^5 \\ -5z^5 - 3z^3 - 3\bar{z}^3 - 5\bar{z}^5 \\ 8iz^4 - 8i\bar{z}^4 \end{bmatrix} \\ &= \frac{1}{4} \begin{bmatrix} -5z^7 + 3z^5 + 5z^3 - 3z - 3\bar{z} + 5\bar{z}^3 + 3\bar{z}^5 - 5\bar{z}^7 \\ 5iz^7 + 3iz^5 - 5iz^3 - 3iz + 3i\bar{z} + 5i\bar{z}^3 - 3i\bar{z}^5 - 5i\bar{z}^7 \\ 8z^6 - 8z^2 - 8\bar{z}^2 + 8\bar{z}^6 \end{bmatrix} \\ (\psi k_\theta)_z &= \frac{1}{4} \begin{bmatrix} -35z^6 + 15z^4 + 15z^2 - 3 \\ 35iz^6 + 15iz^4 - 15iz^2 - 3i \\ 48z^5 - 16z \end{bmatrix} \\ (\psi k_\theta)_z u_z &= \frac{1}{4} \begin{bmatrix} -35z^6 + 15z^4 + 15z^2 - 3 \\ 35iz^6 + 15iz^4 - 15iz^2 - 3i \\ 48z^5 - 16z \end{bmatrix} \begin{bmatrix} 1 - z^2 \\ i(1 + z^2) \\ 2z \end{bmatrix} \\ &= -z^6 + z^2 \\ z((\psi k_\theta)_z u_z \psi) &= z(-z^6 + z^2) \left( \frac{z^2 - \bar{z}^2}{2} \right) \\ &= \frac{1}{2} (-z^9 - z^5 - z) \end{aligned}$$

Since this is analytic, its integral around  $S^1$  is zero, so the second term in (2) is zero. That completes the proof of the lemma.

## 1.9 The fourth variation of Enneper's surface

We will compute the fourth variation of Enneper's surface along the path given by

$$u(t, \theta) = u_0(\theta + t\psi) \quad \text{with } \psi = 2 \sin 2\theta$$

We write  $k = u_t = \psi u_\theta$ . Since  $\psi$  does not depend on  $t$ , we have  $k_t = \psi u_{\theta t} = \psi k_\theta$ . The following formula for the fourth variation in a direction belonging to the kernel of the second variation is given in [4].

$$\begin{aligned} \left. \frac{\partial^4 E}{\partial t^4} \right|_{t=0} &= 8 \operatorname{Re} \int z k_z k_{zt} \psi \, dz + 4 \operatorname{Re} \int z k_{ttz} u_z \psi \, dz \\ &\quad + 12 \operatorname{Re} \int z k_{zt} u_z \psi_t \, dz + 8 \operatorname{Re} \int z k_z^2 \psi_t \, dz \end{aligned}$$

Since we have assumed  $\psi_t = 0$  the last two terms can be dropped:

$$\left. \frac{\partial^4 E}{\partial t^4} \right|_{t=0} = 8 \operatorname{Re} \int z k_z k_{zt} \psi \, dz + 4 \operatorname{Re} \int z k_{ttz} u_z \psi \, dz$$

We have

$$\psi = \sin \theta = \frac{1}{2}(-iz^2 + iz^{-2}),$$

By (1),  $k_z$  is divisible by  $z^2$ . Hence  $k_z \psi$  is holomorphic. Since the  $z$ -derivative of any harmonic function is holomorphic, and  $k_t$  is harmonic, so  $k_{zt} = k_{tz}$  is holomorphic. Hence the first term also vanishes:

$$\left. \frac{\partial^4 E}{\partial t^4} \right|_{t=0} = 4 \operatorname{Re} \int z k_{ttz} u_z \psi \, dz$$

Recall from (1) that (even when  $t \neq 0$ )

$$k_z = \frac{1}{4} \begin{bmatrix} 5z^4 - 3z^2 \\ -5iz^4 - 3iz^2 \\ -8z^3 \end{bmatrix}$$

To use this equation when  $t \neq 0$  we should put  $z = e^{i(\theta+t\psi)}$ , so we have

$$z_t = i\psi z$$

Differentiating  $k_z$  with respect to  $t$  we obtain

$$\begin{aligned} k_{zt} &= \frac{1}{4} \frac{\partial}{\partial t} \begin{bmatrix} 5z^4 - 3z^2 \\ -5iz^4 - 3iz^2 \\ -8z^3 \end{bmatrix} \\ &= \frac{z_t}{4} \begin{bmatrix} 20z^3 - 6z \\ -20iz^3 - 6iz \\ -24z^2 \end{bmatrix} \end{aligned}$$

$$\begin{aligned}
&= \frac{i}{4} \psi z \begin{bmatrix} 20z^3 - 6z \\ -20iz^3 - 6iz \\ -24z^2 \end{bmatrix} \\
&= \frac{i}{4} \frac{z^2 - \bar{z}^2}{2i} z \begin{bmatrix} 20z^3 - 6z \\ -20iz^3 - 6iz \\ -24z^2 \end{bmatrix} \\
&= \frac{1}{8} \begin{bmatrix} 20z^6 - 6z^4 - 20z^2 + 6 \\ -20iz^6 - 6iz^4 + 20iz^2 + 6i \\ -24z^4 + 24 \end{bmatrix}
\end{aligned}$$

This came out holomorphic, as it had to, since it is also  $k_{tz}$  and  $k_t$  is harmonic. Now differentiate again with respect to  $t$ :

$$\begin{aligned}
k_{ztt} &= \frac{z_t}{8} \begin{bmatrix} 120z^5 - 24z^3 - 40z \\ -120iz^5 - 24iz^3 + 40iz \\ -96z^3 \end{bmatrix} \\
&= \frac{i\psi z}{8} \begin{bmatrix} 120z^5 - 24z^3 - 40z \\ -120iz^5 - 24iz^3 + 40iz \\ -96z^3 \end{bmatrix} \\
&= \frac{i}{8} \frac{z^2 - \bar{z}^2}{2i} z \begin{bmatrix} 120z^5 - 24z^3 - 40z \\ -120iz^5 - 24iz^3 + 40iz \\ -96z^3 \end{bmatrix} \\
&= \frac{1}{16} \begin{bmatrix} 120z^8 - 24z^6 - 160z^4 + 24z^2 + 40 \\ -120iz^8 - 24iz^6 - 80iz^4 + 24iz^2 - 40i \\ -96z^6 + 96z^2 \end{bmatrix}
\end{aligned}$$

For Enneper's surface we have

$$zu_z = \begin{bmatrix} z - z^3 \\ iz + iz^3 \\ 2z^2 \end{bmatrix}$$

Taking the dot product with the previous equation, we have

$$\begin{aligned}
zk_{ttz}u_z &= \frac{1}{16} \begin{bmatrix} 120z^8 - 24z^6 - 160z^4 + 24z^2 + 40 \\ -120iz^8 - 24iz^6 - 80iz^4 + 24iz^2 - 40i \\ -96z^6 + 96z^2 \end{bmatrix} \cdot \begin{bmatrix} z - z^3 \\ iz + iz^3 \\ 2z^2 \end{bmatrix} \\
&= 5z + O(z^2)
\end{aligned}$$

Multiplying by  $\psi$  we have

$$\begin{aligned}
zk_{ttz}u_z\psi &= (5z + O(z^2)) \frac{z^2 - z^{-2}}{2i} \\
&= 5iz^{-1} + O(1)
\end{aligned}$$

Integrating this around  $S^1$ , the  $O(1)$  part is holomorphic, so it integrates to 0, and we have

$$\begin{aligned}
\left. \frac{\partial^4 E}{\partial t^4} \right|_{t=0} &= 4 \operatorname{Re} \int z k_{t t z} u_z \psi dz \\
&= 4 \operatorname{Re} \int \frac{5i}{z} dz \\
&= 4 \operatorname{Re} \frac{5i}{2\pi i} \quad \text{by Cauchy's residue theorem} \\
&= \frac{10}{\pi}
\end{aligned}$$

We have proved

$$\left. \frac{\partial^4 E}{\partial t^4} \right|_{t=0} > 0 \tag{3}$$

### 1.10 Relative minimum for $R = 1$

We need the following theorem, which is discussed in [4].

**Theorem 1** *Let  $u$  be a minimal surface of disk type bounded by a Jordan curve  $\Gamma$ . Suppose that  $D^2 E(u)$  has a one-dimensional kernel (aside from the conformal directions) and that for some one-parameter family  $u(t)$  of harmonic surfaces bounded by  $\Gamma$ , with  $u(0) = u$  and  $u_t(0) = k$  in the kernel of  $D^2 E(u)$ , the third and fourth derivatives of  $E(u(t))$  with respect to  $t$  are respectively zero and positive. Then  $u$  is a relative minimum of Dirichlet's energy.*

**Corollary 1** *Enneper's surface for  $R = 1$  is a relative minimum of area.*

*Proof.* Let  $u$  be Enneper's surface for  $R = 1$ , and let  $\psi = \sin 2\theta$ . Let  $u(t, \theta) = u(\theta + t\psi)$ . We have calculated the required second, third, and fourth derivatives of  $E(u(t))$  in the previous sections, and they meet the hypotheses of the theorem. That completes the proof.



### 1.11 Trifurcation and the cusp catastrophe

## 2 The catenoid

### 2.1 Weierstrass representation

### 2.2 Non-parametric form

### 2.3 Unique minimal surface of revolution

### 2.4 Existence between coaxial circles in parallel planes

### 2.5 Stability

### 2.6 The second variation

## 3 The helicoid

### 3.1 Weierstrass representation

### 3.2 Non-parametric form

### 3.3 Unique ruled minimal surface

### 3.4 Second variation of $D^2A$

### 3.5 The second, third, and fourth variations of $D^2E$

### 3.6 Trifurcation and the cusp catastrophe

## 4 Scherk's surface

### 4.1 Weierstrass representation

### 4.2 Non-parametric form

### 4.3 Use as a comparison surface

## References

- [1] Axler, S., Bourdon, P., and Ramey, W., *Harmonic Function Theory, second edition*, Springer (2000).
- [2] Beeson, M., Some results on finiteness in Plateau's problem, Part I, Preprint No. 286, Sonderforschungsbereich 72, Universität Bonn, 1972. The last half was later published as [3]; the results of the first part are in Chapter 6 of these lectures.
- [3] Beeson, M., Some results on finiteness in Plateau's problem, Part I, *Math Zeitschrift* **175** (1980) 103–123.

- [4] Beeson, M., Higher variations of Dirichlet's integral and area, unpublished notes available by request.
- [5] Böhme, R., Die Zusammenhangskomponenten der Lösungen analytischer Plateauprob-  
leme, *Math. Zeitschrift* **133** (1973) 31–40.
- [6] Böhme, R., and Tomi, F., Zur structure der Lösungsmenge des Plateauprob-  
lems, *Math. Zeitschrift* **133** (1973) 1–29.
- [7] Böhme, R., and Tromba, A. J., The index theorem for classical minimal  
surfaces, *Annals of Mathematics* **113** 2, 447–499 (1981).
- [8] Courant, R., *Dirichlet's Principle, Conformal Mapping, and Minimal Sur-  
faces*, Interscience (1950), reprinted by Springer-Verlag (1977).
- [9] Courant, R., and Hilbert, D., *Methods of Mathematical Physics, volume 1*,  
Interscience (1962).
- [10] Ulrich Dierkes, Stefan Hildebrandt, and Anthony J. Tromba, *Regularity of  
Minimal Surfaces*, revised and enlarged 2nd edition, Springer (2010).
- [11] Evans, L., *Partial Differential Equations*, AMS (1991).
- [12] Garabedian, P. R., *Partial Differential Equations*, Wiley, New York (1964).
- [13] Hellwig, G., *Partielle Differential-Gleichungen*, B. G. Teubner Verlagge-  
sellschaft, Stuttgart (1960).
- [14] Dierkes, U., Hildebrandt, S., Küster, A., and Wohlrab, O., *Minimal Sur-  
faces I*, Springer-Verlag (1991).
- [15] Dierkes, U., Hildebrandt, S., Küster, A., and Wohlrab, O., *Minimal Sur-  
faces II*, Springer-Verlag (1994).
- [16] Kreyszig, Erwin, *Differential Geometry*, Dover, New York (1991).
- [17] Nitsche, J.C.C., *Lectures on Minimal Surfaces, Vol. 1*, Cambridge Univ.  
Press (1989).
- [18] Osserman, R., *A Survey of Minimal Surfaces*, Dover (1986). The first edi-  
tion was in 1969, but the Dover edition has a chapter on later developments.
- [19] Rado, T., *On the Problem of Plateau*, Springer-Verlag, Berlin (1933). [out  
of print].
- [20] Schuffler, K., Die Variation der konformen Types mehrfach zusam-  
menhängender Minimalflächen,: Anwendung auf die Isoliertheit und Sta-  
bilität des Plateau-problems, Thesis, Saarbrücken (1978).
- [21] Titchmarsh, E. C., *The Theory of Functions*, Second edition, Oxford Univ.  
Press (1939).

- [22] Tomi, F., On the local uniqueness of the problem of least area, *Arch. Rational Mech. Anal.* **52** (1973) 312–318.
- [23] Tromba, A. J., On the number of simply connected minimal surfaces spanning a curve, *Memoirs of the AMS* **12**, No. 194 (1977).
- [24] Tromba, Anthony J., A Theory of Branched Minimal Surfaces, Springer (2012).